## SPECIFICATIONS

MINIATURE ENCODER WITH 8+1 JOYSTICK FUNCTION FOR ONE-FINGER CONTROL, IP56 SEALED
> 12 detents Hall-effect sensed encoder with magnetic indexing
> Center button with 8 joystick directions and center push function
> 1 Mio encoder revolutions, 500k joystick actuations
> Full metal front-end; silver or black
>LED backlit illumination (RGB)
> 2.7 to 5.5 VDC supply, UART interface
> $400 \mu \mathrm{~A}$ stand-by current; ideal for battery powered applications
> 6 positions ZIF or soldering pads connection
> -20 to $+60^{\circ} \mathrm{C}$, IP56 sealed


## POSSIBLE CUSTOMIZATIONS

- Front-end shape and color
- Connectors, cabling and pinning
- IPx7 or IPx8 sealing


## TYPICAL APPICATIONS

- Test \& measurement for outdoor environments
- Cockpit (aviation, transport, construction, etc.)
- Industrial controls

MULTI WHEEL silver


MULTI WHEEL black


## DRAWINGS

DIMENSIONS (mm)



Backlit Illumination


At room temperature, +/- 0.1 mm tolerance.
CIRCUITRY AND PIN ALLOCATION


External magnetic fields may interfere function!

DESCRIPTION
Multi Wheel can be mounted from the front or rear using 2 self-tapping screws (included), driven into the plastic body. The outer $O$-ring provides proper front panel sealing. Connections are made via a 6 position ZIF connector or via available solder pads.

Supply voltage is 2.7 to 5.5 VDC and stand-by current is typically $400 \mu \mathrm{~A}$ (when not actuated and illumination is off). The two-way UART communication interface incorporates Multi Wheel output and a LED control input.

When operating Multi Wheel, each encoder step or joystick actuation generates an 8 bit command over the UART output interface (see communication spec). There is no communication in idle mode.

Activating the on-board solder jumper (see drawing), directs the device after re-powering into a demo mode where LED color changes by actuation (UART output keeps working in demo mode).

## SPECIFICATIONS

## MECHANICAL RATING

| Indexing Resolution: | 12 detents (magnetic indexing) |
| :---: | :---: |
| Switching torque: | 0.5 Ncm (+/-30\%, over temperature range and life) |
| Directional push force: | 1 N (+/-30\%, over temperature range and life) |
| Center push force: | 3 N (+/-30\%, over temperature range and life) |
| Encoder life: | 1 Mio revolutions (over temperature range, at 120 RPM max.) |
| Joystick life: | 500 k actuations (over temperature range, at 2 Hz max.) |
| Connector: | ZIF (6 positions, 0.5 mm pitch, top contacts) and soldering pads |
| Mounting screws: | M2 66 mm , self-tapping (DIN7500), with Torx head, included |
| ELECTRICAL RATING |  |
| Operating voltage (Vcc): | 2.7 to 5.5 VDC (stabilized, $50 \mathrm{mV} \mathrm{Vpp}^{\text {max. ripple) }}$ |
| Current consumption: | $400 \mu \mathrm{~A}$ typ. stand-by (3 VDC, room temperature, backlit illumination off, no actuation) 300 mA max. operation (3VDC, room temperature, backlit illumination at full brightness, white color, actuated) |
| UART interface: | 9.6 k baud, 1 byte non-inverted, even parity, 1 stop bit. UART output remains silent when not actuated. (When sending commands to UART input please maintain a 30 ms minimum interval time). |
| MATERIALS AND FINISHES |  |
| Front-end: | Zinc die-cast, matt chrome plated (silver version) or ED painted (black version) |
| Housing: | Polycarbonate, transparent, UV resistant |
| Sealings: | Outer seal (O-ring); ø1.5 mm, NBR70. Inner seal (gasket); EPDM closed cell foam rubber |
| ENVIRONMENTAL RATING |  |
| Temperature ranges: | -20 to $+60^{\circ} \mathrm{C}$ max. operating and storage |
| Humidity: | $90 \%$ relative humidity max., non-condensing (against front panel, MIL-STD-202G, method 103B, condition B) |
| IP sealing: | IP56 |
| Dielectric strength: | 1,000 VDC during 60 sec. (MIL-STD-202G, method 301) |
| PACKAGING |  |

Packaging: $\quad$ Single piece packed (antistatic bag)

## COMMUNICATION

| ACTION |  |  |  | COMMAND |
| :---: | :---: | :---: | :---: | :---: |
|  | Joystick | A |  | x1dec |
|  |  | B |  | $\times 2 \mathrm{dec}$ |
|  |  | C |  | x3dec |
|  |  | D |  | $\times 4 \mathrm{dec}$ |
|  |  | E |  | $\times 5 \mathrm{dec}$ |
|  |  | F |  | x6dec |
|  |  | G |  | $x 7$ dec |
|  |  | H |  | x8dec |
|  |  | CP (center push) |  | x9dec |
|  |  | Return to steady state |  | 00dec |
|  | Encoder | One step CCW |  | 1 xdec |
|  |  | One step CW |  | 2 dec |
| A command is sent at every changing encoder or joystick situation. |  |  |  |  |
| UART INPUT (LED CONTROL): |  |  |  |  |
| FUNCTION | COMMAND |  | EXPLANATION |  |
| RGB Color | Odec bis 90dec |  | - 0 (default) to 89 (see RGB spectrum below) <br> - 90 is white |  |
| Brightness | 100dec bis 103dec |  | 100 is off (default), 101 is lowest, 103 is highest brightness |  |
| Sign of life request | 255 dec |  | Causes |  |

RGB SPECTRUM:

| 0 Red | 15 | Yellow | 30 | Green | 45 | Turquoise | 60 | Blue | 75 | Violet |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

ORDERING CODE


SLV Standard shape, silver
BLK Standard shape, black

